1. Introduction

Photovoltaic is the direct conversion of light into electricity in form of direct current electricity. Usually the DC/DC converters are used to convert this direct electrical power from one level to another.

There are many types of materials which are used to make of the PV modules. The main problem of these materials is low conversion efficiency which is usually moving from 5% (a-Si) to 25% – 30% (GaAs) [1]. Nowadays, the efficiency of the soft switching DC/DC converters is very high and it is moving around the 97%. But, on the other hand, the efficiency of energy conversion is not good in comparison with abovementioned converter efficiency.

This paper presents the novel concept of MPBC with high efficiency of energy conversion. The high efficiency of energy conversion is ensured by adding five more parallel legs to the conventional SPBC. The suitable algorithm of switches control in particular legs ensures that the almost whole PV output energy from the PV module is effective utilized.

2. Efficiency of energy conversion

Figure 1 explains the problem of efficiency of energy conversion. The impinging sun energy $P_{IN, sun}$ is converted by PV module direct to the electric energy. According to the material from which PV module is built this conversion efficiency is moving from 5% (a-Si) to 30% (GaAs) [1] and [2]. The output PV energy $P_{OUT, PV}$ is equal to the input energy to the converter $P_{IN, con}$.

Let us assume that SPBC is used to adjustment of input energy $P_{IN, con}$ from one level to another.

The function principle of conventional SPBC is well known. When the switch $S$ is turned on the input energy starts to accumulate in form of magnetic field in the inductor $L$. This accumulated inductor energy with input energy (source energy) are delivered to the output $Z$ after switch $S$ is turned off. The average value of the output voltage $U_{DC}$ in continuous conduction mode (CCM) is:

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where duty cycle “z” is ratio between time when the switch S is turned on and the period T, \( z = t_{on}/T \). The theoretical waveforms and topology of conventional SPBC are shown in Fig. 2.

It can be seen that there exists a time interval within the period \( T \) when the energy delivered to the load \( Z \) is equal to zero. This is the main problem of conventional SPBC – effective utilization of input energy. We have to ensure that the input energy will be delivered to the load \( Z \) over the whole period \( T \). We have to remove the time interval within the period \( T \) where the energy delivered to the load \( Z \) is zero. The another important fact is, that in case of unfavorable operating conditions of PV module, the SPBC is unable to obtain its maximum power point (MPP).

It stands to reason that the efficiency of energy conversion is very low because we are unable to utilize the whole potential of input energy.

This is done by using the proposed MPBC, [3] and [4]. The three different efficiencies can be defined as:

The conversion efficiency of PV module \( \eta_{PV} \):

\[
\eta_{PV} = \frac{P_{OUT, PV}}{P_{IN}} \tag{2}
\]

The converter efficiency \( \eta_{con} \):

\[
\eta_{con} = \frac{P_{OUT, con}}{P_{IN, con}} \tag{3}
\]

The efficiency of energy conversion \( \eta_{E} \):

\[
\eta_{E} = \frac{P_{OUT, con, MPP}}{P_{GET, PV, MPP}} \tag{4}
\]

where \( P_{GET, PV, MPP} \) is the instantaneous maximal output power of PV module for its certain operating conditions.

3. The proposed concept of MPBC

The proposed topology of MPBC is in Fig. 3a. The MPBC has, in comparison with the conventional SPBC, five more parallel legs with five inductors \( (L_1 - L_6) \), five rectifier diodes \( (D_2 - D_6) \) and five switches \( (S_2 - S_6) \).

This MPBC allows the effective utilization of energy delivered form the PV module. Appropriate control algorithm of switches allows converter to take the PV output energy by cooperation of all six parallel legs in every moment.

4. Principle of operation

The principle of operation of SPBC was mentioned above. This described process can be repeated six times because six parallel legs are presented in proposed MPBC which allows effective utili-

The proposed MPBC has 6 operating cycles within each period. The corresponding operation waveforms are shown in Fig. 3b.

Mode 1 \((t_0 - t_1)\): The switch \( S_1 \) (leg A) is turned on at the time \( t_0 \). The energy in form of magnetic field begins to accumulate in inductor \( L_1 \). The input current is closed in loop \(+U_{IN} - L_1 - S_1 - -U_{IN} \). In this mode the switches \( S_1 \) (leg E) and \( S_6 \) (leg F) are in on-state. The input energy is delivered to the inductor \( L_1 \) and \( L_6 \) in particular legs, too. The switches \( S_2 \) and \( S_1 \) (leg C) are in off-state. The inductor energy \( W_{L1} \) and \( W_{L2} \) is delivered through diodes \( D_2 \) and \( D_1 \) to the load \( Z \). The equivalent equations are:

The inductor voltages \( u_{L1}(t) \), \( u_{L2}(t) \) and \( u_{L6}(t) \) are:

\[
u_{L1}(t) = u_{L2}(t) = u_{L6}(t) = U_{IN} = \frac{dL_{1,2,6}i_{L1,2,6}(t)}{dt} \tag{5}
\]

The inductor voltage \( u_{L2}(t) \), \( u_{L3}(t) \) and \( u_{L4}(t) \) are:

\[
u_{L2}(t) = u_{L3}(t) = u_{L4}(t) = U_{IN} - U_{oc} = L_{3,4} \frac{di_{L2,3,4}(t)}{dt} \tag{6}
\]

The currents flow through inductors \( L_1 \), \( L_3 \), \( L_6 \) and switches \( S_1 \), \( S_3 \), \( S_6 \) are.
The currents flow through inductors L2, L3, L4 and diodes D2, D3, D4 are:

\[
i_{L2}(t) = i_{L3}(t) = i_{D2}(t) = i_{D3}(t) = i_{L4}(t) =
\]
\[
= i_{L5}(t) = \frac{1}{L_{156}} \int_{t_0}^{t} u_{L156}(t) dt + I_{156}(t)
\]
\[
= \frac{U_{in}}{L_{156}}(t - t_s) + I_{156}(t_s)
\]
\[
\text{The currents flow through inductors L1, L5, L6 and couple of diodes D1, D5, D6 are}
\]
\[
i_{L1}(t) = i_{L5}(t) = i_{L6}(t) = i_{D1}(t) = i_{D5}(t) = i_{D6}(t) =
\]
\[
= i_{L6}(t) = \frac{1}{L_{156}} \int_{t_0}^{t} u_{L156}(t) dt + I_{156}(t)
\]
\[
= \frac{U_{in} - U_{out}}{L_{156}}(t - t_s) + I_{156}(t_s)
\]

The inductor current \( i_{L2}(t) \) exponentially increases from the initial value \( I_{L2} \) to the maximum value \( I_{L1max} \) (reached at the time \( t_s \)) with time constant \( \tau_1 = L_1/R \).

**Mode 2** (\( t_1 - t_2 \)) and **mode 3** (\( t_2 - t_3 \)) are the same as mode 1. Only other switches \( S_1 \) (leg B, mode 2) and \( S_5 \) (leg C, mode 3) are turned on, on-state \( S_1 \), \( S_6 \) (leg A and leg F, mode 2) and \( S_5 \), \( S_6 \) (legs A and B, mode 3) and off-state \( S_3 \), \( S_4 \) (legs D and E, mode 3). The corresponding equations are the same. Only subscripts are changed.

**Mode 4** (\( t_3 - t_4 \)): The switch \( S_1 \) is turned off and \( S_3 \) is turned in the beginning of this mode at the time \( t_1 \). The inductor energy \( W_{L1} \) begins to deliver through diode \( D_1 \) to the load \( Z \). The output current \( i_d(t) \) is enclosed in the loop \( L_1 - D_1 - Z - U_{in} - U_{out} \). The switches \( S_3 \) (leg B) and \( S_5 \) (leg C) are on-state and the input energy is delivered to the inductor \( L_2 \) and \( L_3 \). The switches \( S_1 \) (leg E) and \( S_2 \) (leg F) are in off-state. The inductor energy \( W_{L3} \) is delivered through diodes \( D_3 \) and \( D_4 \) to the load \( Z \). The equivalent equations are:

The inductor voltages \( u_{L1}(t), u_{L2}(t) \) and \( u_{L3}(t) \) are

\[
u_{L1}(t) = u_{L2}(t) = u_{L3}(t) = U_{in} = \frac{d i_{L156}(t)}{dt}
\]
\[
\text{The inductor voltages} \ u_{L1}(t), u_{L2}(t) \text{and} \ u_{L3}(t) \text{are}
\]
\[
u_{L2}(t) = u_{L3}(t) = u_{L1}(t) = U_{in} - U_{out} = \frac{d i_{L156}(t)}{dt}
\]
\[
\text{The currents flow through inductors} \ L_1, L_2, L_3 \text{and switches} \ S_1, S_2, S_3 \text{are}
\]
\[
i_{L1}(t) = i_{L2}(t) = i_{L3}(t) = i_{L5}(t) = i_{L6}(t) =
\]
\[
= i_{L5}(t) = \frac{1}{L_{156}} \int_{t_0}^{t} u_{L156}(t) dt + I_{156}(t)
\]
\[
= \frac{U_{in}}{L_{156}}(t - t_s) + I_{156}(t_s)
\]

The inductor current \( i_{L2}(t) \) exponentially increases with time constant \( \tau_1 = L_1/R \).

**Mode 5** (\( t_4 - t_5 \)) and **mode 6** (\( t_5 - t_6 \)) are the same as mode 4. Only other switches \( S_1 \) (leg E, mode 5) and \( S_3 \) (leg F, mode 6) are turned on, on-state \( S_1 \), \( S_5 \) (leg C and leg D, mode 5) and \( S_6 \), \( S_6 \) (legs D and E, mode 6) and off-state \( S_3 \), \( S_4 \) (legs A and B, mode 6) and \( S_5 \), \( S_6 \) (leg A and leg F, mode 5). The corresponding equations are the same. Only subscripts are changed.
5. Simulation Results

The simulation models of MPBC and SPBC shown in Fig. 4 were created in simulation environment OrCAD Capture CSI to verify its theoretical properties. The power MOSFET transistors were used as switches. The two DC voltage sources were used to simulate output photovoltaic voltage $U_{PV}$ and battery voltage $U_{bat}$. Parameters:

- Switching frequency $f_s = 50 \text{ kHz}$
- Output voltage $U_{bat} = 14 \text{ V}$
- Inductance $L = L_1 = L_2 = L_3 = L_4 = L_5 = 100 \mu\text{H}$

Three different levels of input voltage $U_{PV}$ were set to compare the properties of simulation models of MPBC and SPBC. The tested values of input voltage were $U_{PV} = \{2 \text{ V}, 6 \text{ V}, 12 \text{ V}\}$.

Fig. 4 Simulation models of proposed MPBC a) and conventional SPBC b)

Fig. 5 Simulation comparison of basic properties of SPBC (upper part) and MPBC (lower part)
Figure 5 shows gate voltage $U_G$, inductor current $i_L(t)$, diode current $i_D(t)$, and load current $i_Z(t)$ at the different value of input voltage $U_{PV}$. In can be seen that the MPBC works in comparison with SPBC in CCM for whole range of input voltage $U_{PV}$ except the minimum value $U_{PV_{min}} = 2 \text{ V}$. The load current $i_Z(t)$ is sum of currents in particular legs which delivers its energy to the load $Z$. The waveforms of three legs of MPBC are displayed for lucidity.

Control structures created in Simulink environment are shown in Fig. 6, [5]-[7]. For this purpose the PSpice SLPS (Simulink PSpice) simulation environment was used. This environment supports the substitution of an actual Simulink block with an equivalent analog PSpice electrical circuit. The simulation models of SPBC and MPBC are completely included to the simulink model control design by means of SLPS block.

Figures 7a and 8a show overall view of load current $i_Z(t)$, inductor current $i_L(t)$, input voltage $U_{PV}$, and duty cycle $z$ of SPBC and MPBC. From the detailed analysis (Figs. 7b, 7c and 8b) it is clear that the MPBC works in comparison with SPBC in CCM for the whole range of input voltages $U_{PV}$ except the minimum value $U_{PV_{min}} = 2 \text{ V}$.

6. Experimental results

The laboratory models of SPBC and proposed MPBC were built and tested to verify the theoretical assumptions and simulation results. The laboratory model of control structure of MPBC was built and connected to the converter to generate corresponding gate signals for transistors in particular legs. Figure 9 shows the overall view connection of converter with designed control.

The DC regulated voltage source was used to simulate different operating conditions and thus different levels of output PV voltage $U_{PV}$. The battery was used as a load $Z$. 

**Fig. 6** Simulink models of control structure of SPBC (upper part) and conventional MPBC (lower part)

**Fig. 7** Waveforms of photovoltaic voltage $U_{PV}$, duty cycle $z$, inductor current $i_L(t)$ and load current $i_Z(t)$ of SPBC
Figures 10 and 11 show input voltage $U_{PV}$, gate voltage $U_G$, input current $I_{PV}$ and load current $i_Z(t)$, of SPBC and MPBC. It is clear that the load current $i_Z(t)$ is continually delivered to the load $Z$. Even if input voltage $U_{PV}$ is set to the minimum value 4 V the maximum input current $I_{PV_{\text{max}}}$ is taken from the input voltage source. This is another important fact in comparison with SPBC. The laboratory model of proposed MPBC works in discontinuous conduction mode at the $U_{PV} = 4$ V in comparison with simulation model. This is because the real components were used in comparison with the simulation model where many of parasitic and physical properties cannot be taken into account.

7. Comparison of efficiency of energy conversion

Efficiency of energy conversion $\eta_E$ can be defined as a ratio of output converter energy $P_{OUT_{\text{con}}}$ to the maximum output energy $P_{OUT_{\text{PV,MPP}}}$ of PV module which it is able to deliver under the given operating conditions. It is evident, that the efficiency of energy conversion $\eta_E$ of MPBC is several times higher in comparison with SPBC, Fig. 12, for the whole range of operating conditions. The low efficiency of energy conversion $\eta_E$ of SPBC results from its principle of operation. The SPBC operates in pulse mode so only a portion of its input energy is delivered to output. The PV module operates...
in MPP point for whole range of operating conditions, or more precisely, for the whole range of input photovoltaic voltage $U_{pv}$ when the MPBC is used.

8. Conclusion

The most popular material used to make the solar cell is silicon ($Si$). The $Si$ is also one of major factors in long-term energy recovery and high cost of PV modules. One way to reduce the long-term energy and financial recovery is to use the proposed MPBC. The MPBC works with high efficiency of energy conversion in comparison with SPBC. The MPBC continually delivers the input source energy to the load $Z$ using six parallel phases. In this case, the time interval when the output energy is equal to zero is removed. The MPBC ensures that the PV module is operating in the maximum power point for whole range of its operating conditions, so we can effectively utilize the output PV energy.

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References