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A NOTE ON USING GRAPHS IN REGULAR SCHEDULING PROBLEMS

This paper deals with regular permutation scheduling on graphs. Peško and Czimmermann introduced this problem (in [3]) and it is a generalisation of a matrix permutation problem. The goal is to minimise differences between row sums of a real matrix that represents a schedule, but external conditions don't allow moving matrix elements arbitrarily. The conditions can be represented by permutation obtained from a certain graph.

1. Introduction

The matrix permutation problem (MPP) is to minimise differences between row sums by permuting elements in columns of a matrix. This problem was defined first by Š. Peško in [5]. The exact definition of MPP (from [1]) is:

There is given matrix $(a_{i,j}) \in R^{m \times n}$ (we will call it scheduling matrix). We need to find permutations of the numbers $1, \dots, m$, $\pi_j = (\pi_j(1), \dots, \pi_j(i))$ for $j = 1, \dots, n$ such that a certain Schur-convex function $f(s_1, \dots, s_m)$ is minimal (where s_i is the sum of elements in i -th row $s_i = \sum_{j=1}^n a_{\pi_j(i),j}$). The most used Schur-convex functions are:

- $f_{sq}(s_1, \dots, s_m) = s_1^2 + s_2^2 + \dots + s_m^2$
- $f_{dif}(s_1, \dots, s_m) = \max(s_1, \dots, s_m) - \min(s_1, \dots, s_m)$
- $f_{max}(s_1, \dots, s_m) = \max(s_1, \dots, s_m)$
- $f_{sq}^\delta(s_1, \dots, s_m) = (s_1 - \delta)^2 + \dots + (s_m - \delta)^2$ where $\delta = \frac{(s_1, \dots, s_m)}{m}$

In [7] it was shown that MPP is NP-hard except two column case for which the polynomial algorithm was found ([2]).

We can gain a generalisation of MPP, if we will not limit ourselves to column permutations and permutations will be allowed by a certain graph (its vertices represent elements of a scheduling matrix, element $a_{i,j}$ is represented by the vertex $v_{i,j}$). We will call it *regular permutation scheduling on graphs* (RPSG). In [3] there were given two ways how to generate needed permutations. We can use:

1. graph of permitted moves,
2. graph automorphisms.

(The graph of permitted moves will be denoted GPM and the related problem GPM-P.)

2. Graph of permitted moves

In this section we will continue in our work started in [3]. It is known from this work that MPP can be solved as a special case of GPM-P and if GPM is a complete digraph with loops on every vertex, two-column case can be solved for irregularity measure f_{sq} as a minimal perfect matching in a certain complete graph. Unfortunately there exist graphs of permitted moves for which two column case can't be solved as a minimal perfect matching in a graph (it was one of the open problems introduced in [3] related to two column GPM-P).

Example 1. In Figure 1 we can see the graph of permitted moves G_M and related graph G whose vertex set is the same as the vertex set of G_M and vertices $v_{i,j}, v_{k,l}$ are connected by an edge of weight $w = (a_{i,j} + a_{k,l})^2$ if and only if there exist directed edges $(v_{i,j}, v_{x,y})$ and $(v_{k,l}, v_{x,z})$ in G_M ($y, z \in [1, 2], y \neq z$) it means that $a_{i,j}$ and $a_{k,l}$ could form the row in a new matrix). We can see that for perfect matching with edges $v_{1,1}, v_{1,2}, v_{2,1}, v_{2,2}$ and $v_{3,1}, v_{3,2}$ there doesn't exist any permitted permutation of elements of the matrix A for which elements $a_{1,1}, a_{1,2}$ form some row of new scheduling matrix and elements $a_{2,1}, a_{2,2}$ another one.

If we use for two column case another Schur-convex function f and we can transform GPM to a graph in which we find perfect matching then the solution of GPM-P will be perfect matching that minimises f .

Example 2. There is given a matrix $A_{3 \times 2} = (a_{i,j})$, GPM is a complete directed graph with loop on every vertex and $f_{max}(s_1, s_2, s_3) = \max(s_1, s_2, s_3)$ is the irregularity measure. We can solve this problem as finding the perfect matching with minimal $f_{max}(s_1, s_2, s_3)$ in a complete graph with the same vertex set as GPM has (where s_1, s_2, s_3 are weights of edges used in this matching and edge $[v_{i,j}, v_{k,l}]$ has weight $a_{i,j} + a_{k,l}$).

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We present an algorithm that finds perfect matching in the graph minimizing the function f_{\max} in graph $G = (V, E)$. (A similar problem is presented in [6] p. 260.)

1. let $n = |V|$ is even and $m = |E|$
2. sort the edges into nondecreasing sequence S

$$S = (\underbrace{e_1, \dots, e_{i_1}}_{c_1}, \underbrace{e_{i_1+1}, \dots, e_{i_2}}_{c_2}, \dots, \underbrace{e_{i_{k-1}+1}, \dots, e_{i_k}}_{c_3})$$

where $i_k = m$ and c_1, \dots, c_k are weights of the edges

3. find $j \in \{1, \dots, k\}$ for which $i_{j-1} + 1 \leq n/2 \leq i_j$
4. if such j does not exist then STOP (there is no perfect matching in G) else let $r := j$
5. delete every edge e in G for which its weight $c(e) > c_r$ (we obtain a graph

$$G' = G - \{e; e \in E, c(e) > c_r\}$$

6. for every edge $e = \{u, v\}$ ($u, v \in V$) of weight $c(e) = c_r$ do:
 - let $G'' = G' - u - v$
 - find perfect matching in G''
 - if M is perfect matching in G'' then STOP (edge e and edges of M form perfect matching in G for which is function f_{\max} minimal)
7. if $r < k$ then $r := r + 1$ and go to 5 else STOP there isn't any perfect matching in G .

It isn't hard to show that the presented algorithm is polynomial. In step 2 it makes $O(n^2 \log n)$ steps. An $O(n^{5/2})$ algorithm is known for finding perfect matching in graphs [4, 6] and this algo-

rithm must be made $m < n^2$ times at most so that our algorithm has complexity $O(n^{9/2})$.

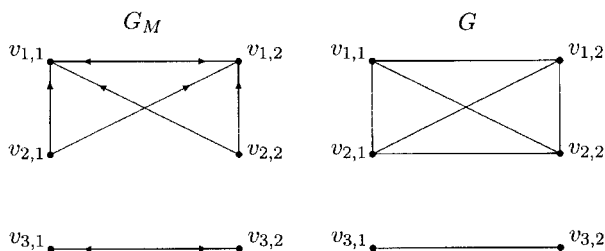


Fig. 1. Graphs G_M and G

3. Conclusions

In this paper we dealt with using the graphs in regular scheduling problems. It seems that perfect matching that is minimal with consideration to some Schur-convex function is an important concept. For most Schur-convex functions f it remains an open problem to find an polynomial algorithm for perfect matching that is minimal with consideration to f . Similarly, two column case is unsolved if perfect matching can't be used for representing a convenient solution.

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